NICOLA BEZZO

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Academic Positions

- **Associate Professor** — 08/2022–present
  Electrical and Computer Engineering, Systems Engineering (Courtesy), Computer Science (Courtesy), University of Virginia, Charlottesville, VA USA.
- **Assistant Professor** — 01/2016–08/2022
  Systems Engineeing (Primary), Electrical and Computer Engineering (Secondary), Computer Science (Courtesy), University of Virginia, Charlottesville, VA USA.
- **Postdoctoral Researcher** — 11/2012–12/2015
  Computer Science, University of Pennsylvania, Philadelphia, PA, USA.
- **Research Assistant in Electrical and Computer Engineering** — 08/2008–10/2012
  Electrical and Computer Engineering, University of New Mexico, Albuquerque, NM, USA.
- **Research Assistant in Electrical Engineering** — 09/2007–07/2008
  Electrical Engineering, Politecnico di Milano, Milan, ITALY.

Education

- **Postdoc in Computer Science (Robotics & CPS)** — 11/2012-12/2015
  University of Pennsylvania, Philadelphia, PA, USA (Supervisor: Prof. Insup Lee).
- **Ph.D. in Electrical and Computer Engineering (Robotics & Control Systems)** — 08/2008-10/2012
  University of New Mexico, Albuquerque, NM, USA (Thesis Advisor: Prof. Rafael Fierro).
- **Master of Science in Electrical Engineering** — 08/2006-07/2008
  Politecnico di Milano, Milan, ITALY (Thesis Advisor: Prof. Roberto Ottoboni).
  - Degree with honor (summa cum laude).
- **Exchange Student 1^{st} year of Master in Electrical Engineering** — 08/2006-08/2007
  Oklahoma State University, Stillwater, OK, USA.
  - GPA: 3.9/4.0.
- **Bachelor of Science in Electrical Engineering** — 09/2003-07/2006
  Politecnico di Milano, Milan, ITALY (Thesis Advisor: Prof. Roberto Ottoboni).
  - Degree with honor (summa cum laude).

Honors & Awards

- DARPA Young Faculty Award (2025).
- Recipient of the 2023 UVA Outstanding Researcher Award (2024).
- Elevation to IEEE Senior Member (2023).
- Finalist NIST First Responder UAS 3D Mapping Challenge (2023) – Prize = $15,000
- Recipient of the IEEE Systems & Information Design Symposium (SIEDS) "Best Paper Award" (2024, 2023, 2018).
- Recipient of the 2022 Amazon Faculty Research Award (2022).
- Recipient of the 2022 UVA Mead Endowment - Henry Kinnier Award (2022).

- 2^{nd} Place at the International Conference on Robotics and Automation BARN Challenge (2022).
- Recipient of the IEEE Robotics & Automation Magazine (RAM) "Best Paper Award" (2016).
- Recipient of two DARPA HACMS outstanding service awards (2015, 2013).
- Recipient of the ACM/IEEE International Conference on Cyber Physical Systems (ICCPS), CPSWeek "Best Paper Award" (2014).
- Recipient of the "Outstanding Student Service Award" from the University of New Mexico (2011).
- Awarded the Gold Medal from the Politecnico School of Engineering, for best graduate student in Electrical Engineering (2010).
- N^{o} 2 degrees with honor (summa cum laude) from Politecnico di Milano (2008, 2006).
- Recipient of the "President Honor Roll for Outstanding Academic Performance" from Oklahoma State University (2007).
- Ranked 11^{th} among 30.000 applicants at Politecnico di Milano Entrance Exam (2003).

Student Advisee Awards

- Link Lab Distinguished Research Award (2024) - Lauren Bramblett (SIE PhD'24)
- Outstanding Graduate Student Award (2024) - Lauren Bramblett (SIE PhD'24)
- Best Graduate Student Award (2021) – Esen Yel (SIE PhD'21)
- RSS Pioneer Award (2021) – Esen Yel (SIE PhD'21)
- NSF NRT Fellowship (2021) – Noelle Law (ECE BS'20)
- NSF NRT Fellowship (2021) – William Clark (SIE MS'23)
- Link Lab Student Seminar Award for outstanding research (2020) - Esen Yel (SIE PhD'21)
- 1st place National Collegiate Cyber Defense Competition (CCDC'20) - Maggie Gates (CS MS'20)
- NSF NRT Fellowship (2020) - Jacob Higgins, Electrical Engineering (ECE PhD'24)
- Ruthie Oxford Memorial Award for most promising graduate student (2018) – Esen Yel (SIE PhD'21)
- 2nd place UVA ECE Welcome back Research Poster Award (2018) – Shijie Gao (ECE PhD'24)
- 2nd place UVA ECE Student Research Poster Award (2017) – Atiena Branch (ECE BS'18)

Research Interests

- Robotics, Assured Autonomy, Motion and Task Planning, Control Systems, Sim-to-Real, Reachability Analysis, Unmanned Aerial and Ground Vehicles Applications, Multi-robot and Heterogeneous Systems, Human-robot interaction, Epistemic Planning, CPS Cyber-security

Publications

- **Peer reviewed Journals:**
  - J. Higgins, A. Papadopoulos, E. Bini, **N. Bezzo**. *Optimal Reference Tracking with Arbitrary Sampling*. In Elsevier Automatica, 2025 (TO APPEAR)
  - S. Gao, **N. Bezzo**. *A Schwarz-Christoffel Mapping-based Framework for Sim-to-Real Transfer in Autonomous Robot Operations*. In Springer Journal of Intelligent & Robotic Systems (JINT), 2025 (TO APPEAR)

- L. Bramblett, **N. Bezzo**. *Epistemic Planning for Multi-Robot Systems in Communication Restricted Environments*. In Frontiers in Robotics and AI, 2023 (Special Issue) – Impact = 3.4
- Xuesu Xiao, Zifan Xu, Zizhao Wang, Yunlong Song, Garrett Warnell, Peter Stone, Tingnan Zhang, Shravan Ravi, Gary Wang, Haresh Karnan, Joydeep Biswas, Nicholas Mohammad, Lauren Bramblett, Rahul Peddi, **Nicola Bezzo**, Zhanteng Xie, Philip Dames. *Autonomous Ground Navigation in Highly Constrained Spaces: Lessons Learned From the Benchmark Autonomous Robot Navigation Challenge at ICRA 2022*. In IEEE Robotics and Automation Magazine (RAM), 2022 – Impact = 5.22
- S. Gao, E. Yel, **N. Bezzo**. *Meta-Learning-based Proactive Online Planning for UAVs under Degraded Conditions*. In IEEE Robotics and Automation Letters (RA-L), 2022 – Impact = 5
- R. Peddi, **N. Bezzo**. *An Interpretable Decision Tree-based Virtual Physics Method for Non-interfering Social Planning*. In IEEE Robotics and Automation Letters (RA-L), 2022 – Impact = 5
- P. Bonczek, R. Peddi, S. Gao, **N. Bezzo**. *Detection of Non-random Sign-based Behavior for Resilient Coordination of Robotic Swarms*. In 2022 Transactions on Robotics (TRO) – Impact = 9.4
- J. Higgins, **N. Bezzo**, *Negotiating Visibility for Safe Autonomous Navigation in Occluding and Uncertain Environments*. In IEEE Robotics and Automation Letters (RA-L), 2021 – Impact = 5
- C. Di Franco, **N. Bezzo**, *Interpretable Run-time Monitoring and Replanning for Safe Autonomous Systems Operations*. In IEEE Robotics and Automation Letters (RA-L), 2020 – Impact = 5
- E. Yel, **N. Bezzo**, *Computation-Aware Adaptive Planning and Scheduling for Safe Unmanned Airborne Operations* . In Journal of Intelligent and Robotic Systems (JINT), 2020 – Impact = 3.0
- E. Yel, T. Carpenter, R. Ivanov, C. Di Franco, J. Weimer, I. Lee, **N. Bezzo**, *Assured Run-time Monitoring and Planning: Towards Verification of Deep Neural Networks for Safe Autonomous Operations*. In IEEE Robotics and Automation Magazine (RAM), 2020 – Impact = 5.22
- M. Pajic, J. Weimer, **N. Bezzo**, O. Sokolsky, G. J. Pappas, I. Lee, *Design and Implementation of Attack-Resilient Cyber-Physical Systems* . In IEEE Control Systems Magazine (CSM),. vol. 37, issue 2, pp. 66-81, 2017 – Impact = 6
- **N. Bezzo**, A. Mehta, C. D. Onal, M. T. Tolley, *Robot Makers: The Future of Digital Rapid Design and Fabrication of Robots* . In IEEE Robotics and Automation Magazine (RAM), vol. 22, pp. 27-36, 2015. (**Best Paper Award**) – Impact = 5.33
- **N. Bezzo**, P. Cruz, F. Sorrentino, and R. Fierro, *Decentralized identification and control of networks of coupled mobile platforms through adaptive synchronization of chaos*. In Elsevier Physica D, vol. 267, pp. 94-103, 2014 – Impact = 3.08
- **N. Bezzo**, B. Griffin, P. Cruz, J. Donahue, R. Fierro, and J. Wood, *A Cooperative Heterogeneous Mobile Wireless Mechatronic System* . In IEEE/ASME Transactions on Mechatronics (TMech), vol. 19, no. 1, pp. 20-31, 2014 – Impact = 5.33
- **N. Bezzo**, R. Fierro, A. Swingler, and S. Ferrari, *A Disjunctive Programming Approach for Motion Planning of Mobile Router Networks*. In International Journal of Robotics and Automation (Special Issue), vol. 26, no. 1, pp. 13-25, 2011 – Impact = 1.5

- **Peer reviewed Journals under Review:**
  - J. Higgins, N. Mohammad, **N. Bezzo**. *Data-Driven Occlusion-Aware Navigation via Online Quantile Temporal Difference Learning*. In Journal of Intelligent & Robotic Systems), 2026

- **Peer reviewed Conferences:**
  - J. Reasoner, L. Bramblett, **N. Bezzo**. *Attention-based Higher-Order Reasoning for Implicit Coordination of Multi-Robot Systems*. In IEEE International Conference on Intelligent Robots and Systems (IROS), 2025 (TO APPEAR)
  - N. Mohammad, **N. Bezzo**. *Corridor-based Adaptive Control Barrier & Lyapunov Functions for Safe Mobile Robot Navigation*. In IEEE Conference on Decision and Control (CDC), 2025 (TO APPEAR)

- N. Mohammad, **N. Bezzo**, *A Soft Actor-Critic-based Control Barrier Adaptation for Robust Autonomous Navigation in Unknown Environments*. In IEEE International Conference on Robotics and Automation (ICRA), Atlanta, US, May 19-23, 2025 – Acceptance Rate = 38% (TO APPEAR)
- S. Gao, L. Bramblett, **N. Bezzo**, *Take Your Best Shot: Sampling-Based Next-Best-View Planning for Autonomous Photography & Inspection*. In IEEE International Conference on Robotics and Automation (ICRA), Atlanta, US, May 19-23, 2025 – Acceptance Rate = 38% (TO APPEAR)
- P. Sherman, **N. Bezzo**. *Heterogeneous System of Systems for Proactive Path Planning in Uncertain Environments*. In IEEE International Conference on Intelligent Robots and Systems (IROS), 2024 – Acceptance Rate = 45%
- L. Bramblett, B. Miloradovic,P. Sherman, A. V. Papadopoulos, **N. Bezzo**. *Robust Online Epistemic Replanning of Multi-Robot Missions*. In IEEE International Conference on Intelligent Robots and Systems (IROS), 2024 – Acceptance Rate = 45%
- P. Bonczek, **N. Bezzo**. *A Cooperative Recovery Framework for Resilient Multi-Robot Swarm Operations under Loss of Localization in Unknown Environments*. In IEEE International Conference on Intelligent Robots and Systems (IROS), 2024 – Acceptance Rate = 45%
- N. Mohammad, J. Higgins, **N. Bezzo**, *A GP-based Robust Motion Planning Framework for Agile Autonomous Robot Navigation and Recovery in Unknown Environments*. In IEEE International Conference on Robotics and Automation (ICRA), Yokohama, Japan, May 13-17, 2024 – Acceptance Rate = 44%
- R. Peddi, **N. Bezzo**, *A Decision Tree-based Monitoring and Recovery Framework for Autonomous Robots with Decision Uncertainties*. In IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), Detroit, MI, USA, October 1 - 5, 2023 – Acceptance Rate = 43%
- L. Bramblett, **N. Bezzo**, *Epistemic Planning for Heterogeneous Robotic Systems*. In IEE/RSJ International Conference on Intelligent Robots and Systems (IROS), Detroit, MI, USA, October 1 - 5, 2023 – Acceptance Rate = 43%
- J. Higgins, N. Mohammad, **N. Bezzo**, *A Model Predictive Path Integral Method for Fast, Proactive, and Uncertainty-Aware UAV Planning in Cluttered Environments*. In IEE/RSJ International Conference on Intelligent Robots and Systems (IROS), Detroit, MI, USA, October 1 - 5, 2023 – Acceptance Rate = 43%
- P. Bonczek, **N. Bezzo**, *RSSI-based Localization with Adaptive Noise Covariance Estimation for Resilient Multi-Agent Formations*. In IEEE American Control Conference (ACC), San Diego, CA, USA, May 31 - June 02, 2023 – Acceptance Rate = 50%.
- L. Bramblett, S. Gao, **N. Bezzo**, *Epistemic Prediction and Planning with Implicit Coordination for Multi-Robot Teams in Communication Restricted Environments*.In IEEE International Conference on Robotics and Automation (ICRA), London, UK, May 29 - June 2, 2023 – Acceptance Rate = 45%.
- E. Bini, A. Papadopoulos, J. Higgins, **N. Bezzo**, *Optimal Reference Tracking for Sampled-Data Control Systems*. In IEEE Conference on Decision and Control (CDC), Cancun, Mexico, December 6 - 9, 2022 – Acceptance Rate = 50%.
- L. Bramblett, R. Peddi, **N. Bezzo**, *Coordinated Multi-Agent Exploration & Exploitation of Unknown Environments with Limited Connectivity*. IEE/RSJ International Conference on Intelligent Robots and Systems (IROS), Kyoto, Japan, October 23 - 27, 2022 – Acceptance Rate = 45% .
- N. Mohammad, **N. Bezzo**, *A Robust and Fast Occlusion-based Frontier Method for Autonomous Navigation in Unknown Cluttered Environments*. IEE/RSJ International Conference on Intelligent Robots and Systems (IROS), Kyoto, Japan, October 23 - 27, 2022 – Acceptance Rate = 45%.
- P. Bonczek, **N. Bezzo**, *Resilient Detection and Recovery of Autonomous Systems Operating under on-board Controller Cyber Attacks*. IEE/RSJ International Conference on Intelligent Robots and Systems (IROS), Kyoto, Japan, October 23 - 27, 2022 – Acceptance Rate = 45%.
- M. Cleveland, Esen Yel, Y. Kantaros, I. Lee, **N. Bezzo**, *Learning Enabled Fast Planning and Control in Dynamic Environments with Intermittent Information*. IEE/RSJ International Conference on Intelligent Robots and Systems (IROS), Kyoto, Japan, October 23 - 27, 2022 – Acceptance Rate = 45%.

- J. Higgins, E. Bini, **N. Bezzo**, *Offloaded Receding Horizon Planning for Environments with Variable Communication Delays*. IEEE Conference on Control Technology and Applications (CCTA), Trieste, Italy, August 22 - 25, 2022 – Acceptance Rate = 50%.
- J. Higgins, **N. Bezzo**, *A Model Predictive-based Motion Planning Method for Safe and Agile Traversal of Unknown and Occluding Environments*. In IEEE International Conference on Robotics and Automation (ICRA), Philadelphia, PA, May 23 - 27, 2022 – Acceptance Rate = 45%.
- C. Gall, **N. Bezzo**, *Gaussian Process-based Interpretable Runtime Adaptation for Safe Autonomous Systems Operations in Unstructured Environments*. In IEEE International Conference on Intelligent Robots and Systems (IROS), Prague, Czech Republic, Sept 27 - Oct. 1, 2021 – Acceptance Rate = 45%.
- S. Gao, **N. Bezzo**, *A Conformal Mapping-based Framework for Robot-to-Robot and Sim-to-Real Transfer Learning*. In IEEE International Conference on Intelligent Robots and Systems (IROS), Prague, Czech Republic, Sept 27 - Oct. 1, 2021 – Acceptance Rate = 45%.
- E. Yel, **N. Bezzo**, *A Meta-Learning-based Trajectory Tracking Framework for UAVs under Degraded Conditions*. In IEEE International Conference on Intelligent Robots and Systems (IROS), Prague, Czech Republic, Sept 27 - Oct. 1, 2021 – Acceptance Rate = 45%.
- R. Peddi, **N. Bezzo**, *Interpretable Run-Time Prediction and Planning in Co-Robotic Environments*. In IEEE International Conference on Intelligent Robots and Systems (IROS), Prague, Czech Republic, Sept 27 - Oct. 1, 2021 – Acceptance Rate = 45%.
- P. Bonczek, **N. Bezzo**, *Detection and Inference of Non-random Behavior for Resilient Multi-vehicle Coordinated Operations*. In IEEE International Conference on Intelligent Robots and Systems (IROS), Prague, Czech Republic, Sept 27 - Oct. 1, 2021 – Acceptance Rate = 45%.
- J. Higgins, **N. Bezzo**, *Negotiating Visibility for Safe Autonomous Navigation in Occluding and Uncertain Environments*. In IEEE International Conference on Robotics and Automation (ICRA), Xi'An, China, May 30 - Jun. 5, 2021 – Acceptance Rate = 40%.
- P. Bonczek, **N. Bezzo**, *Detection of Hidden Attacks on Cyber-Physical Systems from Serial Magnitude and Sign Randomness Inconsistencies*. In IEEE American Control Conference (ACC), New Orleans, May 26 - 28, 2021 – Acceptance Rate = 50%.
- E. Yel, **N. Bezzo**, *GP-based Runtime Planning, Learning, and Recovery for Safe UAV Operations under Unforeseen Disturbances*. In IEEE International Conference on Intelligent Robots and Systems (IROS), Las Vegas, NV, Oct. 25 - 29, 2020 – Acceptance Rate = 45%.
- R. Peddi, C. Di Franco, S. Gao, **N. Bezzo**, *A Data-driven Framework for Proactive Intention-Aware Motion Planning of a Robot in a Human Environment*. In IEEE International Conference on Intelligent Robots and Systems (IROS), Las Vegas, NV, Oct. 25 - 29, 2020 – Acceptance Rate = 45%.
- C. Hilderbrandt, S. Elbaum, **N. Bezzo**, MB. Dwyer, *A Feasible and stressful trajectory generation for mobile robots*. In 29th ACM SIGSOFT International Symposium on Software Testing and Analysis (ISSTA), Los Angeles, CA, Jul. 18 - 22, 2020 – Acceptance Rate = 15%.
- C. Di Franco, **N. Bezzo**, *Interpretable Run-time Monitoring and Replanning for Safe Autonomous Systems Operations*. In IEEE International Conference on Robotics and Automation (ICRA), 2020 – Acceptance Rate = 40%.
- C. Hilderbrandt, S. Elbaum, **N. Bezzo**, *Blending Kinematic and Software Models for Tighter Reachability Analysis*. In International Conference on Software Engineering (ICSE), 2020 – Acceptance Rate = 15%.
- P. Bonczek, **N. Bezzo**. *Model-based Randomness Monitor for Stealthy Sensor Attacks*. In 2020 American Control Conference (ACC) – Acceptance Rate = 60%
- P. Bonczek, **N. Bezzo**. *Memoryless Cumulative Sign Detector forStealthy CPS Sensor Attacks* In 2020 International Federation of Automatic Control (IFAC) – Acceptance Rate = 50%
- E. Yel, **N. Bezzo**, *Fast Run-time Monitoring, Replanning, and Recovery for Safe Autonomous System Operations*. In IEEE International Conference on Intelligent Robots and Systems (IROS), Macau, China, Nov. 4 - 8, 2019 – Acceptance Rate = 45%.

- R. Peddi, **N. Bezzo**, *Parameter-free Regression-based Autonomous Control of Off-the-shelf Quadrotor UAVs*. In IEEE International Conference on Unmanned Aerial Systems (ICUAS), Atlanta, GA, June 11 - 14, 2019 – Acceptance Rate = 60%.
- S. Gao, C. Di Franco, D. Carter, D. Quinn, **N. Bezzo**, *Exploiting Ground and Ceiling Effects on Autonomous UAV Motion Planning*. In IEEE International Conference on Unmanned Aerial Systems (ICUAS), Atlanta, GA, June 11 - 14, 2019 – Acceptance Rate = 60%.
- Z. Vatansever, M. Brandt-Pearce, **N. Bezzo**, *Localization in Optical Wireless Sensor Networks for IoT Applications*. In IEEE International Conference on Communications (ICC) May 20, 2019.
- E. Yel, T. Lin, **N. Bezzo**. *Self-triggered Adaptive Planning and Scheduling of UAV Operations*. In 2018 IEEE International Conference on Robotics and Automation (ICRA), Brisbane, Australia, May 21-25 2018, pp. 7518-7524 – Acceptance Rate = 40%.
- T. Lin, **N. Bezzo**. *Energy-aware Persistent Control of Heterogeneous Robotic Systems*. In 2018 American Control Conference (ACC), Milwaukee, WI, June 27-29 2018, pp. 2782-2787 – Acceptance Rate = 50%.
- M. Elnaggar, **N. Bezzo**. *An IRL Approach for Cyber-Physical Attack Intention Prediction and Recovery*. In 2018 American Control Conference (ACC), Milwaukee, WI, June 27-29 2018, pp. 222-227 – Acceptance Rate = 50%.
- E. Yel, T. Lin, **N. Bezzo**. *Reachability-based self-triggered scheduling and replanning of UAV operations*. In 2017 IEEE NASA/ESA Conference of Adaptive Hardware and Systems (AHS), Pasadena, CA, July 24-27 2017, pp. 221-228 – Acceptance Rate = 55%.
- M. Elnaggar, J. D. Hiser, T. Lin, A. Nguyen-Tuong, M. Co, J. W. Davidson, **N. Bezzo**. *Online control adaptation for safe and secure autonomous vehicle operations*. In 2017 NASA/ESA Conference of Adaptive Hardware and Systems (AHS), Pasadena, CA, July 24-27 2017, pp.101-108 – Acceptance Rate = 55%.
- E. Yel, T. Lin, **N. Bezzo**. *Reachability-based self-triggered UAV motion planning*. In 2017 International Symposium on Aerial Robotics, June 19-20 2017 – Acceptance Rate Unknown.
- **N. Bezzo**, K. Mohta, C. Nowzari, I. Lee, V. Kumar, G. Pappas, *Online Planning for Energy-efficient and Disturbance-aware UAV Operations*. In IEEE International Conference on Intelligent Robots and Systems (IROS), Daejeon, South Korea, October 9-14, 2016, pp. 5027-5033 – Acceptance Rate = 45%.
- **N. Bezzo**, J. Weimer, Y. Du, O. Sokolsky, S. H. Son, I. Lee, *A Stochastic Approach for Attack Resilient UAV Motion Planning*. In 2016 American Control Conference (ACC 2016), Boston (MA), July 6-8, 2016, pp. 1366-1372 – Acceptance Rate = 50%.
- Y. Shoukry, P. Nuzzo, **N. Bezzo**, A. L. Sangiovanni-Vincentelli, S. A. Seshia, P. Tabuada, *Secure State Reconstruction in Differentially Flat Systems Under Sensor Attacks Using Satisfiability Modulo Theory Solving*. In IEEE Control and Decision Conference (CDC), Osaka, Japan, Dec. 15 - 18, 2015, pp. 3804-3809 – Acceptance Rate = 56%.
- **N. Bezzo**, M.Piccoli, P. Gebhard, V. Kumar, M. Yim, I. Lee, *Rapid Co-design of electro-mechanical specifications for robotic systems*. In ASME 2015 International Design Engineering Technical Conferences & Computers and Information in Engineering Conference (IDETC/CIE 2015), Boston, MA, Aug. 2 - 5, 2015 – Acceptance Rate = 60%.
- **N. Bezzo**, J. Weimer, M. Pajic, O. Sokolsky, G. J. Pappas, I. Lee, *Attack Resilient State Estimation for Autonomous Robotic Systems*. In IEEE International Conference on Intelligent Robots and Systems (IROS), Chicago, IL, Sept. 14 - 18, 2014, pp. 3692-3698 – Acceptance Rate = 46%.
- J. Weimer, O. Sokolsky, **N. Bezzo**, and I. Lee, *Towards Assurance Cases for Resilient Control Systems*. In IEEE International Conference on Cyber-Physical Systems, Networks, and Application (CPSNA), Hong Kong, China, August 25 - 26, 2014, pp. 1-6. (*Invited Paper*) – Acceptance Rate Unknown.
- A. Mehta, **N. Bezzo**, P. Gebhard, B. An, V. Kumar, I. Lee, and D. Rus, *A Design Environment for the Rapid Specification and Fabrication of Printable Robots*. In International Symposium on Experimental Robotics (ISER), Marrakech/Essaouira, Morocco, June 15 - 18, 2014 – Acceptance Rate Unknown.

- M. Pajic, J. Weimer, **N. Bezzo**, P. Tabuada, O. Sokolsky, I. Lee, and G. J. Pappas, *Robustness of Attack-resilient State Estimators*. In ACM/IEEE International Conference on Cyber-Physical Systems (ICCPS), Berlin, Germany, April 14 - 17, 2014, pp. 163-174 (**Best Paper Award**) – Acceptance Rate = 25%.
- J. Weimer, **N. Bezzo**, M. Pajic, O. Sokolsky, and I. Lee, *Attack-Resilient Minimum Mean-Squared Error Estimation*. In 2014 American Control Conference (ACC 2014), Portland (OR), June 4-6, 2014, pp. 1366-1372 – Acceptance Rate = 50%.
- **N. Bezzo**, F. Sorrentino, and R. Fierro, *Decentralized Estimation of Topology Changes in Wireless Robotic Networks*. In American Control Conference (ACC), Washington D.C., June 17-19, 2013, pp. 5899-5904 – Acceptance Rate = 50%.
- **N. Bezzo**, M. Anderson, and R. Fierro, *A Real World Coordination Framework for Connected Heterogeneous Robotic Systems*. International Symposium on Distributed Autonomous Robotic Systems (DARS), Baltimore, MD, November 8-11, 2012 – Acceptance Rate = 40%.
- **N. Bezzo**, and R. Fierro, *Decentralized Connectivity and User Localization Via Wireless Robotic Networks*. In IEEE Global Communications Conference (GLOBECOM), Wi-UAV, Houston, TX, December 5, 2011, pp. 1285-1290 – Acceptance Rate = 36%.
- **N. Bezzo**, Y. Yuan, R. Fierro, and Y. Mostofi, *A Decentralized Connectivity Strategy for Mobile Router Swarms*. In the 18^{th} World Congress of the International Federation of Automatic Control (IFAC), Milan, Italy, August 30, 2011 – Acceptance Rate = 55%.
- **N. Bezzo**, and R. Fierro, *Swarming of Mobile Router Networks*. In American Control Conference (ACC), San Francisco, CA, July 1, 2011, pp. 4685-4690 – Acceptance Rate = 60%.
- **N. Bezzo**, and R. Fierro, *Tethering of Mobile Router Networks*. In American Control Conference (ACC), Baltimore, MD, June 30, 2010, pp. 6828-6833 – Acceptance Rate = 60%.

- **Peer reviewed Conferences under Review:**
  - J. Reasoner, **N. Bezzo**. *Higher Order Reasoning for Collaborative Mobile Robot Operations in Communication-Denied Environments*. In IEEE International Conference on Robotics and Automation (ICRA), 2026
  - W. Kim, **N. Bezzo**. *Online Adaptation for Robot Motion Planning using Guided Denoising Diffusion Models*. In IEEE International Conference on Robotics and Automation (ICRA), 2026

- **Book Chapters:**
  - A. Mehta, **N. Bezzo**, P. Gebhard, B. An, V. Kumar, I. Lee, and D. Rus, *A Design Environment for the Rapid Specification and Fabrication of Printable Robots*. Book Chapter in Springer STAR series in Robotics, 2015.
  - **N. Bezzo**, and R. Fierro, *A Real World Coordination Framework for Connected Heterogeneous Robotic Systems*. Book Chapter in "Distributed Autonomous Robotic Systems", Springer STAR series in Robotics, vol. 104, pp.75-89, 2014.
  - **N. Bezzo**, R. A. Cortez, and R. Fierro, *Exploiting Heterogeneity in Robotic Networks*. Book Chapter in Springer "Redundancy in Robot Manipulators and Multi-Robot Systems" vol. 57, pp. 53-75, 2013.

- **Miscellaneous Other Conferences:**
  - G. Weaver, A. Manalang, P. Sherman, H. Mortveit, **N. Bezzo**, *Toward Robotic Triage: a Distributed Task and Motion Planning Framework for Efficient Human-Robot Emergency Response*. In IEEE Systems and Information Engineering Design Symposium (SIEDS), 2025 (**Honorable Mention Award**).
  - V. Shah, M. Heeter, J. Vallarino, P. Sherman, L. Bramblett, **N. Bezzo**, *Evolutionary-based Coordination of Multi-Robot Systems with Dynamic Constraints*. In IEEE Systems and Information Engineering Design Symposium (SIEDS), pp. 7-12, 2024 (**Best Paper Award**).

- S. Nayhouse, S. Chadha, P. Hourican, C. Moore, **N. Bezzo**, *A General Framework for Human-Drone Interaction under Limited On-board Sensing*. In IEEE Systems and Information Engineering Design Symposium (SIEDS), pp. 308-313, 2023 (**Best Paper Award**).
- G. Glaubit, K. Kleeman, N. Law, J. Thomas, S. Gao, R. Peddi, E. Yel, **N. Bezzo**, *Fast, Safe, and Proactive Runtime Planning and Control of Autonomous Ground Vehicles in Changing Environments* In IEEE Systems and Information Engineering Design Symposium (SIEDS), pp. 1-6, 2021
- S. Wang, N. Anselmo, M. Garrett, R. Remias, M. Trivett, A. Christoffersen, **N. Bezzo**, *Fly-Crash-Recover: A Sensor-based Reactive Framework for Online Collision Recovery of UAVs* In IEEE Systems and Information Engineering Design Symposium (SIEDS), pp. 1-6, 2020
- J. Benko, W. Clark, C. Craig, G. Culver, P. Mahan, A. Patel, D. Voce, **N. Bezzo**, G. Lewin. *Security and Resiliency of Coordinated Autonomous Vehicles*. In IEEE Systems and Information Engineering Design Symposium (SIEDS), pp. 1-6, 2019.
- H. Finegan, S. Jaffe, A. Leon, K. Lytle, E. Morgan, C. Greene, A. Meyer, B. Brinkman, S. De Wekker, H. Yochum, **N. Bezzo**. *Development of an Autonomous Agricultural Vehicle to Measure Soil Respiration*. In Systems and Information Engineering Design Symposium (SIEDS), pp. 1-6. 2019.
- V. Marquis, R. Ho, W. Rainey, M. Kimpel, J. Ghiorzi, W. Cricchi, **N. Bezzo**, *Toward attack-resilient state estimation and control of autonomous cyber-physical systems*. In IEEE Systems and Information Engineering Design Symposium (SIEDS), pp. 70-75, 2018 (**Best Paper Award**).
- R. D. Rosenfeld, M. G. Restrepo, W. H. Gerard, W. E. Bruce, A. A. Branch, G. C. Lewin, **N. Bezzo**, *Unsupervised surface classification to enhance the control performance of a UGV*. In IEEE Systems and Information Engineering Design Symposium (SIEDS), pp. 225-230, 2018.
- C.A. Wolf, R.P. Hardis, S.D. Woodrum, R.S. Galan, H.S. Wichelt, M.C. Metzger, **N. Bezzo**, G. C. Lewin, S.F.J. de Wekker, *Wind data collection techniques on a multi-rotor platform*. In IEEE Systems and Information Engineering Design Symposium (SIEDS), pp. 32-37, 2017.
- Z. Calhoun, P. Maribojoc, N. Selzer, L. Procopi, **N. Bezzo**, C. Fleming, *Analysis of Identity and Access Management alternatives for a multinational information-sharing environment*. In IEEE Systems and Information Engineering Design Symposium (SIEDS), pp. 208-213, 2017.
- M. Pajic, **N. Bezzo**, I. Lee, *Design and Implementation of Attack–Resilient Cyber-Physical Systems*, In High-Confidence Software and Systems Conference (HCSS), Annapolis, MD, May 2016.
- **N. Bezzo**, K. Mohta, V. Kumar, I. Lee, *A Run time Monitoring Framework for Safe Coordination of Unmanned Aerial Vehicles* In Safe and Secure Systems and Software Symposium (S5) , Dayton, OH, 10 June 2015

- **Workshops:**
  - S. Gao, L. Bramblett, **N. Bezzo**. *Next-Best-View-based Task and Motion Planning for Autonomous Photography & Inspection*. In 2023 Workshop on Task and Motion Planning: from Theory to Practice within IEEE International Conference on Intelligent Robots and Systems (IROS), Detroit, MI, October 1-5 2023.
  - E. Yel, **N. Bezzo**. *Reachability-based Adaptive UAV Scheduling and Planning in Cluttered and Dynamic Environments*. In 2018 Workshop on Informative Path Planning and Adaptive Sampling within IEEE International Conference on Robotics and Automation (ICRA), Brisbane, Australia, May 21-25 2018.
  - **N. Bezzo**, Y. Du, O. Sokolsky, and I. Lee, *A Markovian Approach for Attack Resilient Control of Mobile Robotic Systems*. In Second International Workshop on Robotic Sensor Networks (RSN), Seattle, Washington, April 13, 2015.
  - O. Sokolsky, M. Pajic, **N. Bezzo**, and I. Lee, *Architecture-Centric Software Development for Cyber-Physical Systems*. In First Workshop on Cyber-Physical System Architectures and Design Methodologies (CPSArch), New Delhi, India, October 17, 2014.
  - L. Feng, A. L. King, S. Chen, A. Ayoub, J. Park, **N. Bezzo**, O. Sokolsky, and I. Lee *A Safety Argument Strategy for PCA Closed-Loop Systems: A Preliminary Proposal*. In Medical Cyber Physical Systems Workshop (MedicalCPS), Berlin, Germany, April 14, 2014.

- J. Weimer, **N. Bezzo**, M. Pajic, G. J. Pappas, O. Sokolsky, and I. Lee, *Resilient Parameter-Invariant Control with Application to Vehicle Cruise Control*. In Workshop on Control of Cyber-Physical Systems, Johns Hopkins University, Baltimore, MD, March 2013.
- **N. Bezzo**, and R. Fierro, *Mobile Robotic Routers Networks*. In Workshop on Frontiers of Real-World Multi-Robot Systems: Challenges and Opportunities, Duke University, Durham, NC, October 10-11, 2011
- **N. Bezzo**, P. Cruz, I. Palunko, T. Appel, D. Galarowicz, and R. Fierro, *The MARHES heterogeneous multi robot test bed* . In 1st Southwest Workshop on Cyber-Physical Systems, University of Arizona, Tucson, AZ, March 10-11 2011.

- **Demos and Abstracts:**
  - **N. Bezzo**, J. Park, A. King, P. Gebhard, R. Ivanov, I. Lee, *Demo Abstract: ROSLab – A Modular Programming Environment for Robotic Applications*. Demonstration at the 5th ACM/IEEE International Conference on Cyber-Physical Systems (ICCPS, CPSWEEK 2014), Berlin, Germany, April 2014, pp. 214-214.
  - M. Pajic, **N. Bezzo**, J. Weimer, O. Sokolsky, N. Michael, G. J. Pappas, P. Tabuada, and I. Lee, *Demo Abstract: Synthesis of Platform-aware Attack-Resilient Vehicular Systems*. Demonstration at the 4th ACM/IEEE International Conference on Cyber-Physical Systems (ICCPS, CPSWEEK 2013), Philadelphia, Pennsylvania, April 2013, pp. 251-251.
  - M. Pajic, **N. Bezzo**, J. Weimer, R. Alur, R. Mangharam, N. Michael, G. J. Pappas, P. Tabuada, and I. Lee, *Towards synthesis of platform-aware attack-resilient control systems*. Work-in-Progress Abstract at the 4th ACM/IEEE International Conference on Cyber-Physical Systems (ICCPS, CPSWEEK 2013), Philadelphia, Pennsylvania, April 2013.

- **Posters:**
  - S. Gao, L. Bramblett, **N. Bezzo** *Next-Best-View-based Task and Motion Planning for Autonomous Photography & Inspection*. International Conference on Intelligent Robots and Systems, Detroit, October 1 2023.
  - J. Higgins, **N. Bezzo** *Negotiating Visibility for Safe Autonomous Navigation in Occluding and Uncertain Environments*. University of Virginia Research Symposium, UVA, April 8 2021.
  - P. Bonczek, **N. Bezzo** *Cumulative Sign Detector for Stealthy Attacks on Mobile Robotic Swarms*. University of Virginia Research Symposium, UVA, April 7 2020.
  - S. Gao, C. Di Franco, **N. Bezzo** *Exploiting Ground and Ceiling Effects on Autonomous UAV Motion Planning*. ECE Welcome back Research Poster Award, UVA, September 4 2018 (**Best poster award).**
  - E. Yel, **N. Bezzo** *Reachability-based Self-triggered Scheduling and Replanning of UAV Operations*. Student Research Poster Session, UVA, August 21 2017.
  - A. Branch, H. Dean, **N. Bezzo** *Toward Assisted Robotics Perimeter & Surface Mapping*. Student Research Poster Session, UVA, August 21 2017 (**Best poster award).**
  - V. Saraiya, **N. Bezzo** *Toward Disturbance Rejection Control of Autonomous Aerial Vehicles*. Student Research Poster Session, UVA, August 21 2017.

- **Competitions:**
  - N. Mohammad, J. Reasoner, W. Kim, **N. Bezzo** *BARN Challenge.* International Conference on Robotics and Automation (ICRA), Atlanta, 2025 – **invited**
  - N. Mohammad, L. Bramblett, **N. Bezzo** *BARN Challenge*. International Conference on Robotics and Automation (ICRA), London, 2023 – **4th place**
  - N. Mohammad, L. Bramblett, **N. Bezzo** *NIST First Responder UAS 3D Mapping Challenge*. NIST, Salina, KS, 2023 – **Finalist - Prize awarded = $15,000**
  - N. Mohammad, L. Bramblett, S. Gao,R. Peddi, **N. Bezzo** *BARN Challenge*. International Conference on Robotics and Automation (ICRA), Philadelphia, 2022 – **2nd place**

- **Theses and Technical Reports**
  - J. Higgins, **N. Bezzo** *Occlusion-Aware Navigation of Autonomous Mobile Robots in Unknown, Unstructured and Dynamic Environments*. PhD Thesis, July 2024
  - L. Bramblett, **N. Bezzo** *Foundations of Epistemic Planning for Collaborative Multi-Robot Systems*. PhD Thesis, July 2024
  - S. Gao, **N. Bezzo** *Transfer Learning Methods for Prediction, Replanning, and Adaptations of Autonomous Mobile Robots Under Degraded Conditions*. PhD Thesis, May 2024
  - G. Moore, **N. Bezzo** *Proactive and Attentive Autonomous Navigation and Avoidance of Dynamic and Intermittently-Visible Actors*. MS Thesis, December 2023
  - W. Clark, **N. Bezzo** *Hamiltonian Monte Carlo-Based Risk-Aware Motion Planning of Autonomous Robots Subject to Uncertainty*. MS Thesis, May 2023
  - R. Peddi, **N. Bezzo** *Interpretable Monitoring for Self and Socially Aware Mobile Robot Planning*. PhD Thesis, December 2022
  - P. Bonczek, **N. Bezzo** *Randomness-Based Behavior Monitoring for Resilient Autonomous Robot Operations*. PhD Thesis, December 2022
  - N. Mohammad, **N. Bezzo** *Occlusion-Aware Motion Planning of Autonomous Robots in Cluttered and Unknown Environments*. MS Thesis, May 2022
  - E. Yel, **N. Bezzo** *Online Predictive Monitoring and Proactive Planning for Safe Autonomous Robot Operations*. PhD Thesis, July 2021
  - P. Seaton, **N. Bezzo** *Towards Trustworthy Swarming of Autonomous Vehicles*. MS Thesis, December 2021
  - M. Gates, **N. Bezzo** *Towards Trustworthy Swarming of Autonomous Vehicles*. MS Thesis, October 2020
  - T. Lin, **N. Bezzo** *Robust Robotic Operations in the Presence of Uncertainties*. MS Thesis, April 2018
  - **N. Bezzo** *Coordination Strategies for Connected Robotic Networks*. PhD Thesis, October 2012
  - **N. Bezzo**, J. Piovesan, R. Fierro, *Path Planning of Mobile Routers via Antenna Diversity*, SBIR Report, Marhes Laboratory, School of Electrical Computer Engineering, University of New Mexico, August 2011
  - **N. Bezzo** *Low-Cost CMOS Non-Contact Profilometer*. MS Thesis, July 2008
  - **N. Bezzo** *A Sensors Array for the Measurement of Electrical Currents (in italian – Array di Sensori per la Misura di Correnti Elettriche)*. BS Thesis, July 2006

- **Software Artifacts**
  - **N. Bezzo**, P. Gebhard, J. Park, I. Lee, *ROSLab:* a high-level programming environment for robotic applications `http://precise.github.io/ROSLab/`
  - **N. Bezzo**, P. Gebhard, M. Piccoli, I. Lee, *EMLab:* a high-level co-design environment for PCB electro-mechanical specifications.

Citation Count, H-index and i10-index

- **Google Scholar as of Dec 16, 2025:**
  - citation count = 1661
  - h-index = 19
  - i10-index = 44

Graduate Students

- **Current PhD Students:**
  - Lainey Gordon (SIE) – Projected Defense in 2030
  - Jonathan Reasoner (ECE) – Projected Defense in 2027
  - Woosung Kim (SIE) – Projected Defense in 2029
  - Nick Mohammad (ECE) – Projected Defense in 2026 (passed Qualifying exam)
  - Patrick Sherman (ECE) – Projected Defense in 2027 (passed Qualifying exam)

- **Former PhD Students:**
  - Shijie Gao (Ph.D. ECE 2024) – Now Robotics Software Engineer at DiDi Research America
  - Jacob Higgins (Ph.D. ECE 2024) – Now Robotics Software Engineer at Zoox
  - Lauren Bramblett (Ph.D. SIE 2024) – Now Data Scientist in the US Air Force
  - Rahul Peddi (Ph.D. SIE 2022) – Now Senior Software Systems Engineer at Zoox
  - Paul Bonczek (Ph.D. ECE 2022) – Now Senior Tracking Systems and Data Fusion Engineer at the Johns Hopkins University Applied Physics Laboratory
  - Esen Yel (Ph.D. SIE 2021; Postdoc Stanford 2023) – Now Assistant Professor at Rensselaer Polytechnic Institute (RPI)

- **Former MS Students:**
  - Avaneen Pinninti (M.S. CS 2024)
  - Garret Moore (M.S. CS 2023) – Now Senior Robotic Systems Engineer at MITRE
  - William Clark (M.S. SIE 2023) – Now Senior Software Systems Engineer at Metron
  - Pravardhan Nagireddy (MCS CS 2022) – Now Robotics Engineer at Advanced Robotics
  - Tianhao Wu (MCS CS 2022)
  - Phillip Seaton (M.S. ECE 2021)
  - Christian Gall (M.S. ECE 2021) – Exchange student from TUM
  - Mary Margaret Gates (M.S. CS 2020)
  - Tony Lin (M.S. ECE 2018, PhD Georgia Tech 2024) – Now Robotics Research Scientist at the Naval Research Laboratory
  - Vishaal Saraiya (M.S. MAE 2017) – Now Robotics Engineer at Apellix
  - Bradley Hallier (M.S. ECE 2016 -2017)
  - Rahul Vasist (UPenn PRECISE Center, M.S. CS 2015) – Now Firmware Engineer at Oracle
  - Yanwei Du (UPenn GRASP Lab, M.S. ME 2015) – Now PhD student at Georgia Tech

Undergraduate Students

- **Current Undergraduate Students:**
  - Lucas Kohler (B.S. CS 2027)
  - Rui Wang (B.S. CS 2027)
  - Shreepa Partaje (B.S. CS 2025)
  - Zachariah Risheq (B.S. CS 2026)
  - Abigail Manalang (B.S. SIE 2025)
  - Grace Weaver (B.S. SIE 2025)

- **Former Undergraduate Students:**
  - Leila Troxell (B.S. ECE 2025)

- Amelia Nist (B.S. ECE 2025)
- Kailey Brown (B.S. ECE 2025)
- Shrinidi Nadgouda (B.S. ECE 2025)
- Vihar Shah (B.S. SIE 2024)
- Jose Vallarino (B.S. SIE 2024)
- Matthew Heeter (B.S. SIE 2024)
- Oliver Olsen (B.S. SIE 2023)
- Kenny Chundu (B.S. ECE 2023)
- Sammy Nayhouse (B.S. SIE/ECE 2023)
- Samir Chadha (B.S. ECE 2023)
- Patrick Hourican (B.S. ECE 2023)
- Chase Moore (B.S. ECE 2023)
- Prithvi Kinariwala (B.S. CS 2022)
- Noelle Law (B.S. ECE 2021) – Now PhD at NYU
- Katie Kleeman (B.S. SIE 2021)
- Grace Glaubit (B.S. ESE/CS 2021) – Now Systems Engineer at Amazon
- Jeremiah Thomas (B.S. SIE 2021) – Now PhD at UC Santa Barbara
- Nikilesh Subramaniam (ECE 2021) – Now Electrical Engineer at Amazon
- Nicholas Anselmo (B.S. SIE 2020)
- Miller Garrett (B.S. SIE 2020)
- Shirley Wang (B.S. ECE 2020)
- Ryan Remias (B.S. ECE 2020)
- Matthew Trivett (B.S. SIE 2020)
- Anders Christoffersen (B.S. ECE 2020)
- Rohan Raval (B.S. CS 2019) – Now Software Engineer at UBER Robotics
- William Clark (B.S. MAE 2019)
- Grace Culver (B.S. CS 2019)
- Daniel Voce (B.S. ECE 2019)
- Jennavive Benko (B.S. ECE 2019)
- Candace Craig (B.S. SIE 2019)
- Patrick Mahan (B.S. ECE 2019)
- Ajay Patel (B.S. CS 2019)
- Atiena Branch (B.S. ECE 2018) – Now Software Engineer at Naval Research Lab
- Hazen Dean (B.S. SIE 2018)
- Victoria Marquis (B.S. SIE 2018)
- Rebecca Ho (B.S. SIE 2018)
- William Rainey (B.S. SIE 2018)
- Matthew Kimpel (B.S. SIE 2018)
- Joeseph Ghiorzi (B.S. ECE 2018)
- William Cricchi (B.S. ECE 2018)
- Ryan D. Rosenfeld (B.S. CS 2018)
- Mark G. Restrepo (B.S. SIE 2018)
- William H. Gerard (B.S. MAE 2018)
- Walter E. Bruce (B.S. ECE 2018)
- Tahiya Salam (B.S. CS 2017) – Now PhD at UPenn
- Neeraj Gandhi (B.S. ECE 2017) – Now PhD at UPenn

Postdoctoral Researchers

- Carmelo Di Franco (2019 - 2020) – Now at AiTronik, Italy

External Funding

- **Awarded (Total to the PI = $3,764,000)**
  - *LLM Embodiment for Collaborative Autonomy*; Sponsor: DARPA YFA; Amount: $500,000; Duration: 08/2025 – 09/2027; Role: PI
  - *Human-Robot Interactions for Every-day Collaborative Operations*; Sponsor: Commonwealth Cyber Initiative; Amount: $100,000; Duration: 09/01/2024 – 8/31/2025; Role: PI
  - *Enhancing Human-Robot Collaboration through Mixed Reality Interactions*; Sponsor: Commonwealth Cyber Initiative; Amount: $33,000 (Grant total: $100,000); Duration: 09/01/2024 – 8/31/2025; Role: Co-PI
  - *SBIR - Robust High-Fidelity Energy-Informed Autonomy Framework (RHEIA-F)*; Sponsor: US Air Force; Amount: $20,000 (Grant total: $150,000); Duration: 01/01/2024 – 8/31/2024; Role: Co-PI
  - *Robotic Triage*; Sponsor: Northrop Grumman, Amount: $50,000, Gift; Role: PI; 09/2024
  - *Detection, Prediction, and Intent Inference of Cyber-Physical Attacks in Learning-Enabled CPS* ; Sponsor: NSF CHEST; Amount: $50,000; Duration: 08/01/2024 – 12/31/2025; Role: PI
  - *Human-Robot Augmented Reality Smart Inspection*; Sponsor: EnterAR/Siemens; Amount: $10,000; Duration: 09/01/2023 – 5/20/2024; Role: PI
  - *Autonomous Mission Management*; Sponsor: Northrop Grumman, Amount: $100,000, Gift; Role: PI; 09/2023
  - *Voice Control and Motion Planning of Smart UAV for Public Safety*; Sponsor: Commonwealth Cyber Initiative; Amount: $33,000 (Grant total: $100,000); Duration: 09/01/2022 – 2/29/2023; Role: PI
  - *Towards Safe and Agile Robot Navigation in Occluding and Dynamic Environments*; Sponsor: Amazon Research Awards, Amount: $100,000, Gift; Role: PI; 11/2022
  - *Risk-aware Detection, Prediction, and Mitigation in CPS under Cyber-Attack*; Sponsor: NSF CHEST; Amount: $100,000; Duration: 09/01/2022 – 09/01/2023; Role: PI
  - *Autonomous Building Condition Detection and Evaluation (ABCDE)*; Sponsor: CoStar Group; Amount: $1,000,000; Duration: 01/01/2022 – 12/31/2024; Role: PI
  - *Integrated Static and Dynamic Approaches to High-Assurance for Learning-Enabled Cyber-Physical Systems*; Sponsor: DARPA Assured Autonomy Program; Amount: $ 498,000 (Grant total: $5,000,000); Duration: 01/01/2018 – 03/31/2023; Role: Co-PI
  - *Reverse Engineering Methodology for Resilient and Reconfigurable Autonomous CPS*; Sponsor: NSF CHEST; Amount: $100,000; Duration: 08/01/2021 – 07/31/2022; Role: PI
  - *SaTC: CORE: Small: Online Malicious Intent Inference for Safe CPS Operations under Cyber-attacks*; Sponsor: NSF; Amount: $290,642; Duration: 09/01/2018 – 08/31/2022; Role: PI
  - *CRI:II-New: The Living Link Lab: Infrastructure for Enhancing Occupant Experience and Building Operations*; Sponsor: NSF; Amount: $200,000 (Grant total: $754,568); Duration: 09/01/2018 – 08/31/2022; Role: Co-PI
  - *Self-Assurance Modules for Autonomous Systems (SAMAS)*; Sponsor: AFRL; Amount: $50,000; Duration: 03/01/2021 – 05/30/2021; Role: PI
  - *Assured Planning and Control of Heterogeneous Robotics Systems*; Sponsor: LEIDOS; Amount: $100,000 ; Duration: 09/01/2018 – 08/31/2021; Role: PI
  - *Fly-Crash-Recover: Safe Recovery of Faulty UAVs*; Sponsor: MITRE; Amount: $10,000; Duration: 09/01/2019 – 05/31/2020; Role: PI
  - *FPV autonomous drone flight*; Sponsor: MITRE; Amount: $50,000 ; Duration: 09/01/2018 – 12/31/2018; Role: PI

- *Development of Risk-based Attack Resilient State Estimation and Control of CPS* Sponsor: Booz Hallen Hamilton; Amount: $ 10,000; Duration: 08/21/2017 – 05/30/2018; Role: PI
- *Development of Control-Aware Cyber Techniques for Attack-Resilient Industrial Control & Combat Systems* Sponsor: ONR BAA: N00014-16-R-BA04; Amount: $320,000 (Grant total: $2,700,000); Duration:10/01/2016 – 09/30/2020; Role: Co-PI
- *CRitical Information and Infrastructure Identity and access Management Evaluation (CRII-IME)* Sponsor: MITRE; Amount: $10,000; Duration: 09/01/2016 – 05/30/2017; Role: PI
- *Attack-Resilient Autonomous Vehicles* Sponsor: University of Pennsylvania; Amount: $50,000; Duration: 01/01/2016 – 02/28/2017; Role: Co-PI

Internal Funding

- **Awarded (Total = $583,000):**
  - *Purchase of 10 new Turtlebots 4* UVA; 08/2024; Amount: $55,000
  - *The dream about (Autonomous) Flying* UVA Mead Endowment Program; Duration: 9/23/2022 – 9/23/2023; Amount: $3,000
  - *Assessing and enabling effective COVID-19 mitigation strategies to reduce indoor airborne exposures* UVA Internal Engineering in Medicine Award; Duration: 10/1/2020 – 9/30/2021; Amount: $100,000
  - *Towards Learning Enabled Autonomous Infrastructure Inspection* UVA Internal Research Innovation Award; Duration: 7/1/2019 – 6/30/2020; Amount: $60,000
  - *Enabling Robotic Operations in the Real World: A Cloud-based Visible Light Communication Approach* UVA Internal Research Innovation Award; Duration: 6/1/2017 – 8/30/2018; Amount: $75,000
  - *Using flow models to improve quadrotors control and motion-planning* UVA Internal Research Innovation Award; Duration: 6/1/2017 – 8/30/2018; Amount: $50,000
  - *Fully Autonomous Secure and Safe Transport (FASST)* UVA Internal Cyber-security Initiative Award; Duration: 08/29/2016 – 05/15/2017; Amount: $100,000
  - *Cybersecurity Analysis - Cooperative Adaptive Cruise Control* UVA Internal Cyber-security Initiative Award; 08/29/2016 – 05/15/2017; Amount: $60,000
  - *Graduate Curriculum in Robotics and Society* UVA Internal Education Innovation Award; 06/09/2016 – 05/15/2017; Amount: $80,000

Invited Talks

- Presentation at Virginia Tech - Aerospace & Ocean Engineering Seminar *Multi-robot Epistemic Planning*, Blacksburg, VA, 27 November 2023
- Presentation at Amazon *Epistemic Planning of Multi Robotic Systems*, Virtual, 6 September 2023
- Presentation at ETH Zurich - Robotics series *I know that you know that I know: Epistemic Planning of Heterogeneous Robotic Systems*, Virtual, 15 August 2023
- Presentation at ICRA Workshop on Heterogeneity in Multi-Robot Systems *Towards Epistemic Planning of Heterogeneous Robotic Systems*, London, UK, 29 May 2023
- Presentation at Northrop Grumman University Research Symposium (virtual) *Autonomous Mission Management*, Virtual, 28 September 2022
- Presentation at DARPA PI Meeting, University of Pennsylvania, *DNN-based Verified Fast Run-Time Monitoring of Autonomous Systems* , Philadelphia, PA, 8 December 2022
- Presentation at 2021 CS Research Symposium, *Towards Resilient and Agile Autonomous Robots*, UVA, CS, 8 December 2021
- Keynote Presentation at 2021 Galois Balloween Workshop, *Safe and Agile Robot Motion Planing* , Virtual, 28 October 2021

- Presentation at DARPA PI Meeting, *Safe and Fast Planning and Control in Dynamic Environments* , Virtual, 14 October 2021
- Presentation at ICRA *Workshop on Security and Privacy for Robotics*, Paris, France, 27 May 2020
- Presentation at DARPA PI Meeting, University of Minnesota, *DNN-based Verified Fast Run-Time Monitoring of Autonomous Systems* , Minneapolis, MN, 16 March 2019
- Presentation at Galois, *Toward Resilient & Assured Autonomous CPS*, Portlan, OR, 19 December 2018
- Presentation at DARPA PI Meeting, UC Berkeley, *Fast Run-Time Monitoring of Autonomous Systems* , Berkeley, CA, 28 November 2018
- Presentation at 2 Accelerated Master's Program in Systems Engineering Seminars, *Toward Resilient & Assured Autonomous CPS*, Darden School, UVA, Charlottesville, VA, 21 September 2018 and 18 October 2019
- Presentation and Tutorial on CPS-cybersecurity to the Defense Intelligence Agency (DIA), UVA, Charlottesville, VA, 06 September 2017
- Presentation at the 2016 Jacobs Technology Days and the Hampton Roads Unmanned Systems Opportunity Exchange *Unmanned Systems Workforce*, Hampton, VA, 22 April 2016
- Presentation at the 2015 Safe and Secure Systems and Software Symposium (S5) *A Run time Monitoring Framework for Safe Coordination of Unmanned Aerial Vehicles*, Dayton, OH, 10 June 2015
- Invited speaker at NASA Jet Propulsion Laboratory, Pasadena, CA, 12 April 2012.
- Invited speaker at USC Robotics Research Lab, Los Angeles, CA, 13 April 2012.

Teaching

- ECE-6060/SYS-6060/CS-6501 "Autonomous Mobile Robots" – Fall '16 '17 '18 '19 '20 '21 '22 '23 '24 '25
- SYS-3062 "Simulation Modeling" – Spring '17 '18 '19 '20 '21 '22 '23
- SYS-4053 "System Design Capstone" – Fall/Spring '17 '18 '19 '20 '21 '22 '23 '24 '25
- SYS-2001 "Systems Engineering Concepts" – Spring '25

Internal Service

- **School Level:**
  - Member of the Reappointment Committee, 2024 - present
  - Member of the Committee on Academic Standards, 2023 - 2024
  - Funding member of the Link Lab, 2017 - present
  - Member of the Cyber-Security Search Committee, 2021, 2018, 2017
  - Member of the Link Lab CPS Search Committee, 2018, 2016
  - Co-organizer of the Link Lab Opening Ceremony, 2018 (Presentation on CPS Autonomy, Demonstrations, and Drone Ribbon-Cutting)
  - Panelist at Undergraduate Research Network's Research Fair, 2018
  - Live Lab Demonstrations to Visitors of the University (from Industry, Government, other schools), 2016 - present
  - Judge for URN Research Symposium, 2016
  - PhD Committee Member:
    - Jingyun Ning, CS, 2026
    - Kayla Boggess, CS, 2025
    - Siddharth Singh, MAE, 2025

    - Zeyu Mu, SIE, 2024
    - Christof Fehrman, Psychology, 2024
    - Ingy ElSayed-Aly, CS, 2024
    - Billy Smith, MAE, 2022
    - Varundev Sukhil, CS, 2021
    - Trey Woodlief, CS, 2020
    - Carl Hildebrandt, CS, 2020
    - Trent Weiss, CS, 2019
    - Steven Hauser, ESE, 2019
    - Yu Sheng, ECE, 2018
    - Dawei Fan, ECE, 2018
    - Masoud Bashiri, SIE, 2017
    - Jihanyu Su, SIE, 2017
    - Xiaomin Lin, SIE, 2017

- **Department Level:**
  - Member of the SIE Chair Hiring Committee, 2024 - 2025
  - Member of the SIE Vision Committee, 2023 - 2025
  - Member of the Faculty Hiring Committee in Operational Research (OR) and Precision Health Initiative (PHI), 2024
  - Member of the SIE P&T Committee, 2022 - 2025
  - Member of the CS P&T Committee, 2022 - 2023
  - Head of the SIE “System Assurance and Resilience" Committee, 2020 - 2023
  - Member of the Faculty Hiring Committee on Cyber-resilience, 2021
  - Member of the Systems & Information Engineering Graduate Studies Committee, 2016 - 2025
  - Member of the Computer Engineering Graduate Studies Committee, 2019 - 2021
  - Open-House Lab demonstrations, 2016 - present

Professional Service

- **Journals, Conferences, and Workshops Organization:**
  - Organizer of the 1st Virginia Robotics Symposium – 2025 - present
  - Associate Editor for IEEE Transactions on Robotics (T-RO) – 2023 - present
  - Associate Editor for IEEE International Conference on Robotics and Automation (ICRA) – 2024
  - Organizing Committee member and Website Chair for 2022 International Conference on Robotics and Automation (ICRA) – 2020 - 2022
  - Associate Editor for Robotics and Automation Letters (RA-L) – 2020 - 2022
  - Program Committee Member of International Conference on Cyber-Physical Systems – 2024, 2023, 2022, 2020, 2019, 2018, 2017
  - Program Committee Member of International Conference on Intelligent Robots and Systems (IROS) – 2023, 2021, 2020, 2019, 2022
  - Session Chair at the International Conference on Robotics and Automation (ICRA) – 2025, 2024, 2023, 2022
  - Session Chair at the International Conference on Intelligent Robots and Systems (IROS) – 2024, 2023, 2022, 2021, 2019
  - Area Chair for Conference on Robot Learning (CoRL) – 2020
  - Guest Editor of IEEE Computer Special Issue on Resiliency in Cyber-Physical Systems – 2019, 2018
  - Session Chair at the International Conference on Cyber-Physical Systems (ICCPS) – 2018.

  - Program Committee Member American Control Conference – 2018
  - Session Chair at the American Control Conference (ACC) – 2018, 2016.
  - Organizer of the "Robot Makers: The future of digital rapid design and fabrication of robots" (RoMa) workshop within the Robotics: Science and Systems (RSS) Conference – 2016, 2014
  - Session Chair at the Adaptive Hardware and Systems Conference (AHS) – 2017.
  - Session Chair at the International Design Engineering Technical Conferences & Computer & Information in Engineering Conference (IDETC/SIE) – 2015.
  - Session Chair of International Symposium of Experimental Robotics (ISER) - Mechanisms Session – 2014.
- **Government Activities**
  - NSF Proposal Panels for SaTC, NRI, RI, FRR, Trailblazer – 2019 - present
- **Reviewer for:**
  - IEEE Robotics and Automation Magazine;
  - IEEE Transactions on Robotics;
  - IEEE Transactions on Automation Science and Engineering;
  - IEEE/ASME Transactions on Mechatronics;
  - IEEE Control Systems Magazine;
  - IEEE Robotics and Automation Letters;
  - Cambridge Robotica;
  - International Conference on Robotics and Automation (ICRA);
  - International Conference on Intelligent Robots and Systems (IROS);
  - Conference on Robot Learning (CoRL);
  - American Control Conference (ACC);
  - Conference on Decision and Control (CDC)
  - Internationa Conference of Cyber-Physical Systems (ICCPS)
- **Member of:**
  - IEEE (Control Systems Society (CSS), Robotics and Automation Society (RAS), Systems, Man, and Cybernetics Society (SMC)) – 2007 - present
  - IEEE RAS Technical Committee (TC) on Multi-Robot Systems (MRS) – 2017 - present

Media/News Coverage

- UVA Engineering Hosts First-Ever Virginia Robotics Symposium *UVA Engineering Hosts First-Ever Virginia Robotics Symposium*, by Bridget Moriarty,, `https://engineering.virginia.edu/news-events/news/uva-engineering-hosts-first-ever-virginia-robotics-symposium`
- SYS-6581/ECE-6501/CS-6501 course's competition featured in UVA News *Whose Robot Conquered the Cardboard Course, Taking Home the Coveted Golden Duckies?*, by Eric Williamson,, `https://engineering.virginia.edu/news-events/news/whose-robot-conquered-cardboard-course-taking-home-coveted-golden-duckies`
- *How Do You Get a Swarm To Think on the Fly? Create 'Empathy' With Other Robots, For One*, by Eric Williamson, `https://engineering.virginia.edu/news-events/news/how-do-you-get-swarm-think-fly-create-empathy-other-robots-one`
- AMR Lab and Research featured in Studio Aperto Mag, Italia 1 TV Station *Intelligenza artificiale per la sicurezza*, by Daniele Compatangelo , `https://mediasetinfinity.mediaset.it/video/studioapertomag/intelligenza-artificiale-per-la-sicurezza_F312329301289C03`

- SYS-6581/ECE-6501/CS-6501 course's competition featured in UVA Today *Putting It All on the Line*, by Audra Book ,, https://news.virginia.edu/content/putting-it-all-line
- *AMR Spot featured in Dean West SEAS Vision Campaign*, by Elizabeth Mather, https://www.youtube.com/watch?v=PGSLZZDtT_E
- *UVA welcomes Spot the Robot*, by Christopher Tyree and in CBS News, https://engineering.virginia.edu/news/2021/04/see-spot https://www.cbs19news.com/story/43688379/uva-welcomes-spot-the-robot
- SYS-6581/ECE-6501/CS-6501 "Autonomous Mobile Robots" course's competition featured in UVA News Article, *UVA Engineering Professor Outmaneuvers the Pandemic to Build a Better Competition*, https://news.virginia.edu/content/navigating-obstacles-engineering-students-compete-robot-challenge-virtually
- *Two AMR quadrotors were featured in the ribbon cutting ceremony of the Link Lab*, Link Lab Opening Ceremony, https://www.wvtf.org/post/new-uva-lab-aims-combine-teaching-research-and-emerging-technology#stream/0
- *The Autonomous Mobile Robots Lab at UVA*, by Mitchell Powers, UVA Today Video, https://news.virginia.edu/video/UVAs-mobile-autonomous-robots-lab
- *With the Rise of Autonomous Vehicles, Hackers Pose a Serious New Threat*, by Matt Kelly, UVA Today, https://news.virginia.edu/content/rise-autonomous-vehicles-hackers-pose-serious-new-threat
- *Robot, take the wheel: In University lab, engineers teach autonomous vehicles to navigate an unpredictable world*, by Caroline Kettlewell, VIRGINIA Magazine, https://UVAmagazine.org/articles/robot_take_the_wheel
- *Robot makers: The future of digital rapid design and fabrication of robots*, in RoboHub, https://robohub.org/robot-makers-the-future-of-digital-rapid-design-and-fabrication-of-robots/
- *UVA Professor, Students Use Robot to Help Restore Claudius Crozet black Ridge Tunnel*, by Taylor Gleason, NBC29
- *Into the Darkness: UVA Robot Maps Historic Tunnel*, by Matt Kelly, UVA Today, https://news.virginia.edu/content/darkness-UVA-robot-maps-historic-tunnel
- *Two exciting breakthroughs in autonomous vehicle cybersecurity, though questions remain*, in TechRepublic, https://www.techrepublic.com/article/two-breakthroughs-in-autonomous-vehicle-cybersecurity-though-questions-remain/
- *UVA Engineering Lab Brings Students, Professors Together for Collaboration*, by Pete DeLuca, NBC29.
- *Robot mapping news and Lab featured in the wikipedia page for the black Ridge Tunnel*, In Wikipedia, https://en.wikipedia.org/wiki/black_Ridge_Tunnel.
- *University of Virginia Maps Historic Tunnel Using Jackal UGV*, In Robotics Tomorrow and in Clearpath Robotics News, https://www.roboticstomorrow.com/article/2018/01/university-of-virginia-maps-historic-tunnel-using-jackal-ugv/11206.

Personal Information

- Married with 2 kids: Antonio (born 2021) and Anna (born 2024)
- Glider Pilot license – 2002 - present
- Hobbies: Robotics, Piano, Tennis, Cooking
- Spoken Languages: Italian, English